

General Specifications

CMZ900 series

GS 80B10M16E 1st

CMZ900S
GYROCOMPASS

General

A gyrocompass detects the true north by means of a fast-spinning rotor, which is suspended with no friction and is influenced by gravity and rotation of the Earth. A gyrocompass consequently indicates a ship's heading.

CMZ900 series has been type approved in accordance with International Maritime Organization (IMO) standards, resolution A.424 (XI) as well as JIS-F9602, class A standards.

- RESOLUTION A.424(XI)

PERFORMANCE STANDARDS FOR GYRO-COMPASSES

Certificate number of type approval

- JG: Under application (Gyrocompass CMZ900)

No. 4309 (Repeater compass MKR050)

- MED: Under application

- CCS: Scheduled

Features

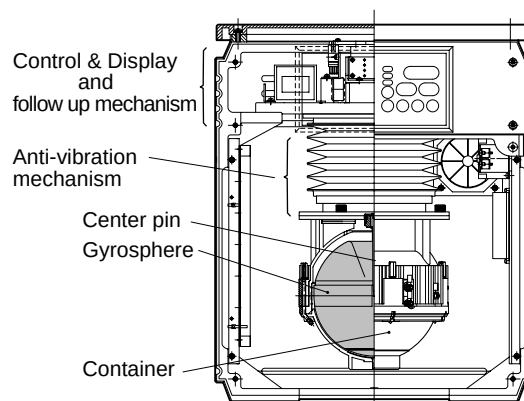
- 1) A modular design saves the space. Master compass can be integrated in the autopilot steering stand.
- 2) Manual and automatic speed error correction
- 3) External heading sensor can back up the heading outputs.
- 4) Heading deviation monitoring
- 5) Steering mode input inhibits the unusual operation of Master compass and secure the current heading information during auto-steering mode.
- 6) Serial data output IEC 61162-2 (high-speed transmission)
- 7) A unique anti-vibration mechanism enhanced by the velocity damping effect of high viscous oil, provides superior damping of vibration and decoupling of shock at sea.
- 8) A small and lightweight container enhances the follow up speed. The gyrocompass reading changes smoothly and does not lag when a small ship rapidly changes course.
- 9) Easy maintenance and long maintenance periods
 - Titanium capsule and electrodes are employed at lower hemisphere of Gyrosphere. Purity is maintained inside of the container, and maintenance interval is then longer-dated.
 - The container is divided into two pieces at bottom when overhauled. Ship's crew can replace Gyrosphere in case of emergency.



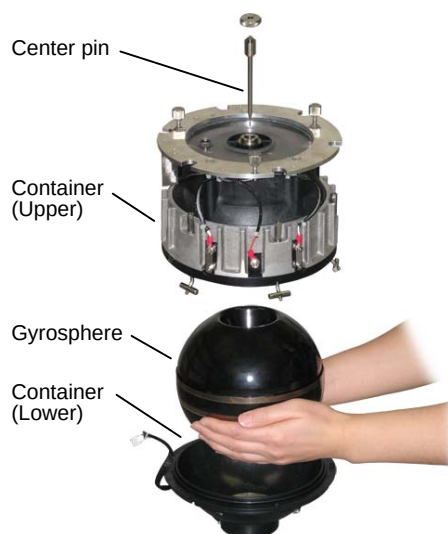
CMZ900S GYROCOMPASS

- MKM026 Master compass

- MKC326 Control box



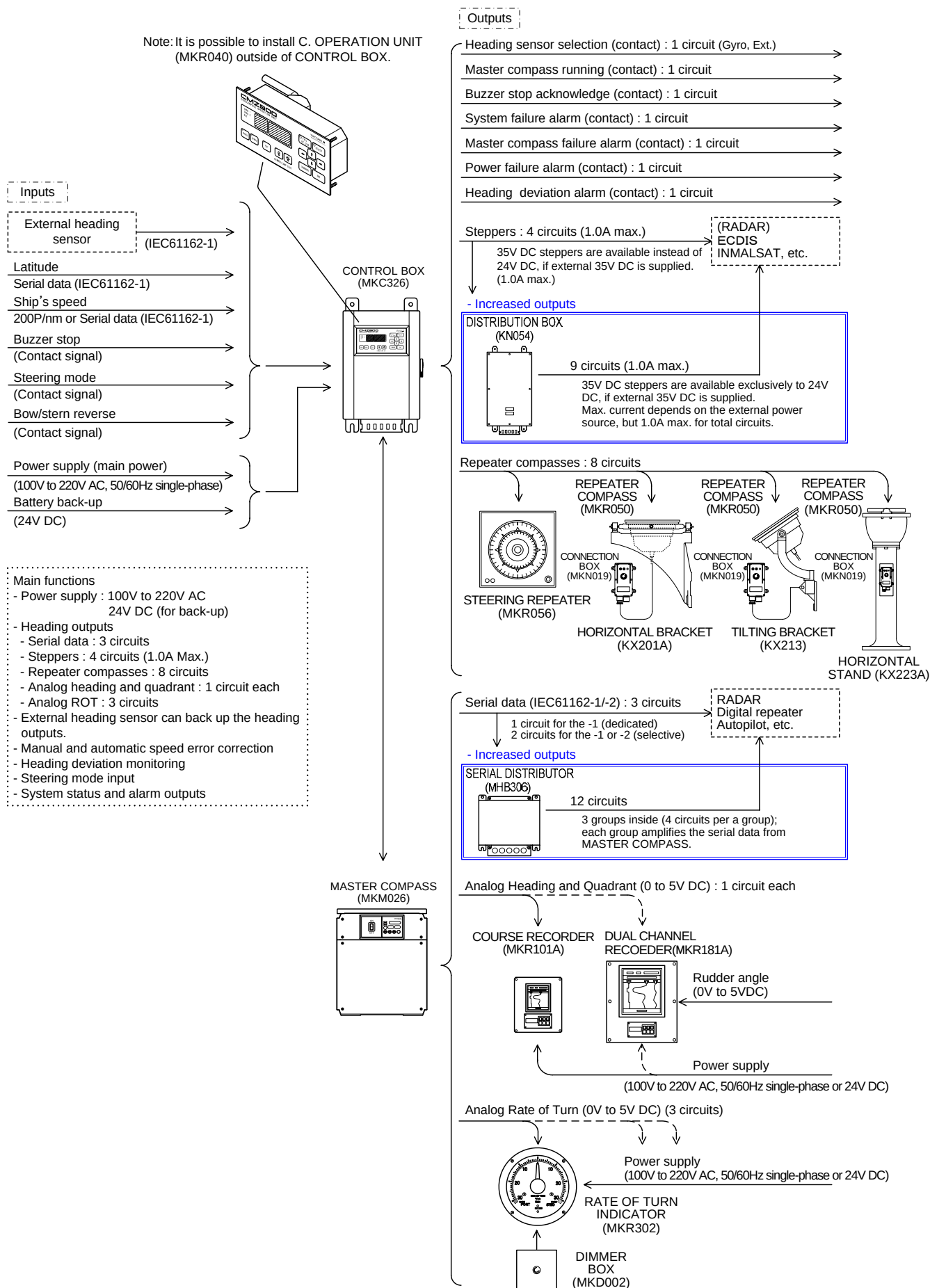
Exposure view of Master compass



Easy maintenance

System configuration diagram

Note: It is possible to install C. OPERATION UNIT (MKR040) outside of CONTROL BOX.



Engineering specifications

- Power supply

Supply voltage

- : 100V / 110V / 115V / 220V AC, 50/60Hz, shingle-phase
- : 24V DC (20V to 30V DC) for back-up

Power consumption at AC drive

- : Starting approx. 125VA
- + 12VA x number of repeater compasses (Max. 8)
- : Operating approx. 100VA
- + 12VA x number of repeater compasses (Max. 8)

Power consumption at DC drive

- : Starting approx. 4.7A
- + 0.35A x number of repeater compasses (Max. 8)
- : Operating approx. 3.5A
- + 0.35A x number of repeater compasses (Max. 8)

- Signal inputs

- Serial data

Serial interface : IEC61162-1

This interface is provided to accept the external heading data as well as ship's speed and latitude data for the automatic speed error correction.

- No. of circuits : 3 circuits
- 1 circuit for Ship's speed
 - 1 circuit for Latitude
 - 1 circuit for Ext. heading sensor

Note: Multiple data input is available from the external single talker.

Transmission convention: Serial asynchronous form

Signaling rate : 4800 bps

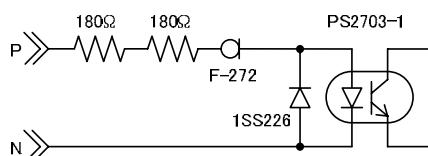
ID & formatter :

ID & formatter	Content
xx ¹⁾ VBW	Dual ground/water speed
xx ¹⁾ VHW	Water speed and heading
xx ¹⁾ VTG	Course over ground and ground speed
VM VSD	Water speed and heading (Yokogawa inherent)
xx ¹⁾ GGA	GPS fix data
xx ¹⁾ GLL	Geographic position, latitude/longitude
xx ¹⁾ HDT	Heading, true
xx ¹⁾ THS	True heading and status
xx ¹⁾ HDG	Heading, deviation and variation
xx ¹⁾ HDM	Heading, magnetic
xx ²⁾ HRC	Heading/ROT (Yokogawa inherent)

Note 1) Any Talker ID "xx" can be received.

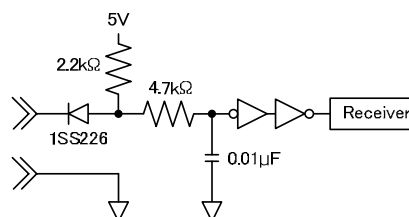
2) Talker ID "xx" of HRC sentence is HE or HC.

Receive circuit (Typical): Photo-coupler



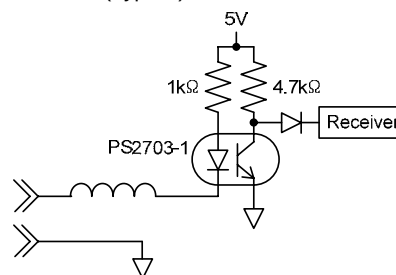
- Ship's speed (pulse input)

- Data source : Ship's speed sensor
- No. of circuits : 1 circuit
- Pulse rate : 200 pulse/n mile
- Signal format : Open collector (photo-coupler) or contact
- Source voltage : 5V DC
- Source current : 2mA
- Receive circuit (Typical)



- Buzzer stop (contact)

- No. of circuits : 1 circuit
- Contact action : Momentary close to command
- Source voltage : 5V DC
- Source current : 5mA
- Receive circuit (Typical)



- Steering mode (contact)

- No. of circuits : 1 circuit
- Contact action : Close and hold to continually use the current heading sensor and to inhibit the unusual operation of Master compass during auto-steering mode
- Source voltage : 5V DC
- Source current : 5mA

- Bow/stern reverse (contact)

- No. of circuits : 1 circuit
- Contact action : Close and hold to reverse
- Source voltage : 5V DC
- Source current : 5mA

- Signal outputs

- Repeater compasses (heading signal)

No. of circuits : 8 circuits
 Electrical characteristics: RS422 (use a driver circuit equivalent to RS422A.)
 Transmission convention: Serial asynchronous form
 Signaling rate : 9600bps
 Transmission interval : 50ms
 Characters : Start bit 1 bit
 Data bit 8 bit
 Stop bit 1 bit
 Parity bit none

ID, formatter and transmission interval:

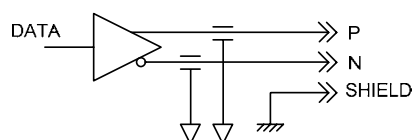
ID & formatter	Transmission interval
HEHDT	50ms
xx ¹⁾ HRC	1s
PYDKH ²⁾	1s

Note 1) Talker ID "xx" of HRC is HE or HC.

2) Yokogawa inherent format

Output circuit (Typical)

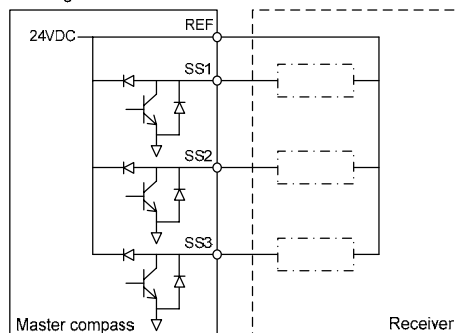
RS422 driver LTC486



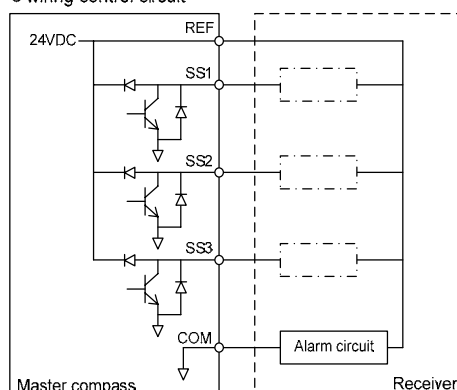
- Steppers (heading signal)

No. of circuits : 4 circuits
 COM : 0V (circuit GND)
 REF output voltage : 24V DC or 35V DC (Option)
 REF output current : 0.3A max. or 1A max. (Option)
 Output form : Open collector (3-bit gray code)
 Sink current : 0.4A max. any signal line

4 wiring control circuit



5 wiring control circuit



- Serial data

Serial interface : IEC61162-1 or -2
 No. of circuits : 3 circuits
 1 circuit for the -1 (dedicated)
 2 circuits for the -1 or -2 (selective)
 Electrical characteristics: RS422 (use a driver circuit equivalent to RS422A.)
 Transmission convention: Serial asynchronous form
 Signaling rate and transmission interval:

	Signaling rate	Transmission interval
IEC61162-1	4800bps	200/500/1000ms selective
IEC61162-2	38400bps	20ms

ID & formatter:

Data source		Content
Gyro	Ext. sensor	
HEHDT	xx ¹⁾ HDT ²⁾	Heading, true
HETHS	xx ¹⁾ THS ²⁾	True heading and status
-	xx ¹⁾ HDG	Heading, deviation and variation
	xx ¹⁾ HDM	Heading, magnetic
HEROT	xx ¹⁾ ROT	Rate of turn ³⁾
HEHRC ⁴⁾	xx ¹⁾ HRC	Heading / Rate of turn ³⁾

Note 1) Talker ID "xx" is subjected to the ext. sensor's ID.

2) Applied in case Transmitting Heading Device (THD) is employed as the ext. sensor.

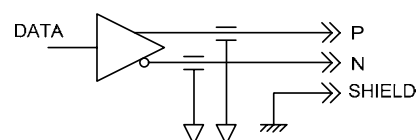
3) Rate of turn is internally calculated (default) or transferred from the ext. sensor (selective).

4) Formatter "HRC" is Yokogawa inherent.

5) Any circuit can transmit up to 3 records as far as the transmission interval allows.

Output circuit (Typical)

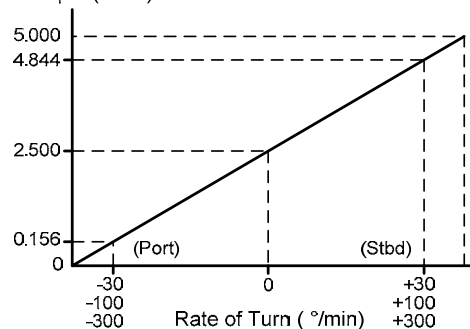
RS422 driver LTC486



- Analog Rate of Turn (ROT)

No. of circuits : 3 circuits
 COM : 0V (circuit GND)
 Output voltage : 0V to 5V DC
 Output resolution : 2.5mV
 Output impedance : 2kΩ max.
 Input impedance of load : 500kΩ min.
 Signal format:

Output (VDC)



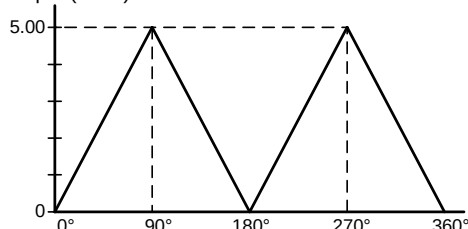
- Analog heading & quadrant signal

No. of circuits : Heading, quadrant both 1 circuit
 COM : 0V (circuit GND)
 Output voltage : 0V to 5V DC
 Output resolution : 2.5mV
 Output impedance : 2k Ω max.
 Input impedance of load : 500k Ω min.
 Accuracy : $\pm 1\%$ (at 25 °C)

Signal format

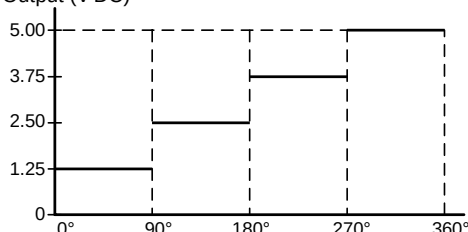
Heading signal

Output (V DC)

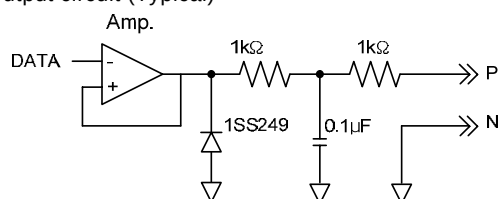


Quadrant signal

Output (V DC)



Output circuit (Typical)

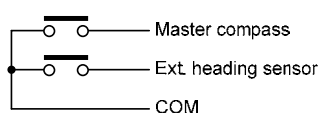


- Heading sensor selection (contact)

No. of circuits : 1 circuit
 Contact action : Closed and held; which represents the heading sensor to transmit

Electrical rating (contact): 24V DC 0.5A

Output circuit



- Master compass running (contact)

No. of circuits : 1 circuit
 Contact action : Closed and held at a running
 Electrical rating (contact): 24V DC 0.5A

- Buzzer stop acknowledge (contact)

No. of circuits : 1 circuit
 Contact action : Momentary closed (1s) when Buzzer stop command is received (Only functional at the system failure condition)

Electrical rating (contact): 24V DC 0.5A

- System failure alarm (contact)

No. of circuits : 1 circuit
 Contact action : Opened and held during malfunction occurs in Master compass or Control box

Electrical rating (contact): 24V DC 0.5A

- Master compass failure alarm (contact)

No. of circuits : 1 circuit
 Contact action : Opened and held during the master compass failure occurs

- Power failure alarm (contact)

No. of circuits : 1 circuit
 Contact action : Opened and held during the power interruption

Electrical rating (contact): 24V DC 0.5A

- Heading deviation alarm (contact)

No. of circuits : 1 circuit
 Contact action : Opened and held at the excess of heading deviation

Electrical rating (contact): 24V DC 0.5A

Performance specifications

1) Settling time : Within 5 hours

(Usable accuracy in approx. 2 hours)

2) Accuracy

- Static : $\pm 0.25^\circ \times \text{sec Lat.}$ (Lat. = latitude)

- Dynamic : $\pm 0.75^\circ \times \text{sec Lat.}$ (Lat. = latitude)

3) Follow-up accuracy : 0.1° or less

4) Maximum follow-up speed : 30°/s

Environmental conditions

1) Permissible roll and pitch angle: $\pm 40^\circ$

2) Permissible vibration

0 to 8.3Hz 3mm_{p-p} or less

8.3 to 25Hz 0.35mm_{p-p} or less

25 to 50Hz 0.1mm_{p-p} or less

3) Permissible ambient temperature

Protected equipments except Master compass

: -15°C to +55°C

Master compass

: -10°C to +50°C

(Operating)

Bering repeater compass : -25°C to +70°C

4) EMC: IEC 60945 4th edition

Paint color

Master compass : Munsell 0.8Y 2.5/0.4 (Lamp Black)

Control box : Munsell 0.8Y 2.5/0.4 (Lamp Black)

System components

This paragraph specifies, hereafter, the outline dimensions (in mm) and Model & Suffix Codes of equipment consisted in CMZ900S. The equipment is listed right and the connection diagram may be covered as far as possible.

Other equipment and accessories listed right are available as a part of CMZ900S. For more detail information, another General Specifications GS80B11K03 is provided.

Equipment and accessories

Model	Nomenclature	Model	Nomenclature
MKM026	Master compass	MKC326	Control box
MKR025	M. Operation unit	MKR040	C. Operation unit
MKR026	Switch unit	MKN018	Junction unit
MKT007	Gyrosphere		
MKZ115	Supporting liquid for installation		
MKZ512	Spare parts		

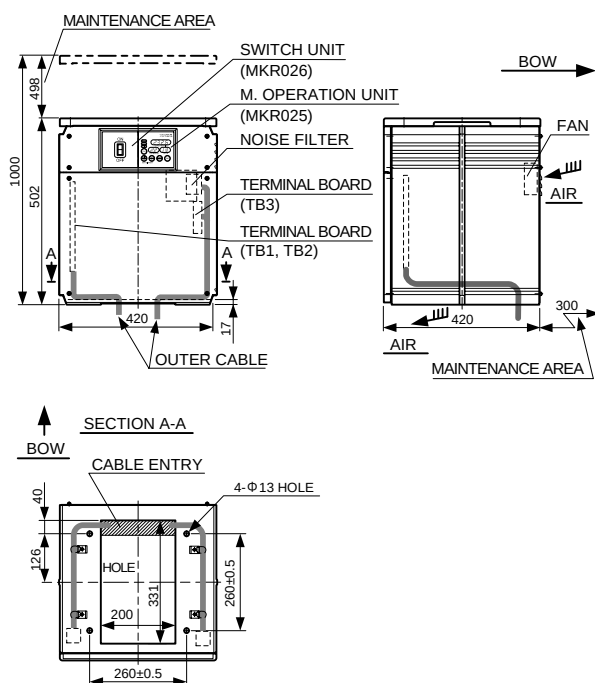
Other equipment and accessories

Model	Nomenclature	Model	Nomenclature
(Analog repeater)		(Digital repeater)	
MKR050	Repeater compass	MHR110A	Universal data display
MKN019	Connection box	MHR112	Assist monitor
KX605	Shading circle	MHR120	Universal data display
KX607	Repeater cover	MKD002	Dimmer box
MKX617	Azimuth circle	(Rate of Turn indicator)	
MKR056	Steering repeater	MKR302	ROT indicator
(Pedestal and bracket)		MKD002	Dimmer box
KX201A	Horizontal bracket	(Recorder)	
KX213	Tilting bracket	MKR101A	Course recorder
KX223A	Horizontal stand	MKR181A	Dual channel recorder
KX607A	Horizontal stand cover	(Signal distributor)	
		KN054	Distribution box (for steppers)
		MHB306	Serial distributor

MKM026 Master compass

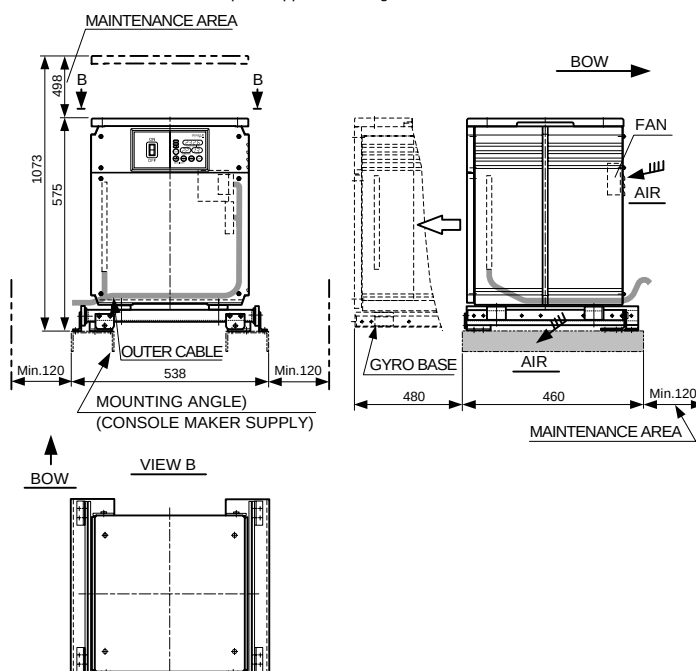
MODEL	MKM026-1
MASS	43 kg

NOTE: Indraft of cable requires approx. 1m long above the bottom of master compass.



MODEL	MKM026-4
MASS	51 kg

Note: 1. GYRO BASE is fastened to MOUNTING ANGLE with bolts.
The MOUNTING ANGLE may be welded to Console.
2. Indraft of cable requires approx. 1m long above the GYRO BASE.

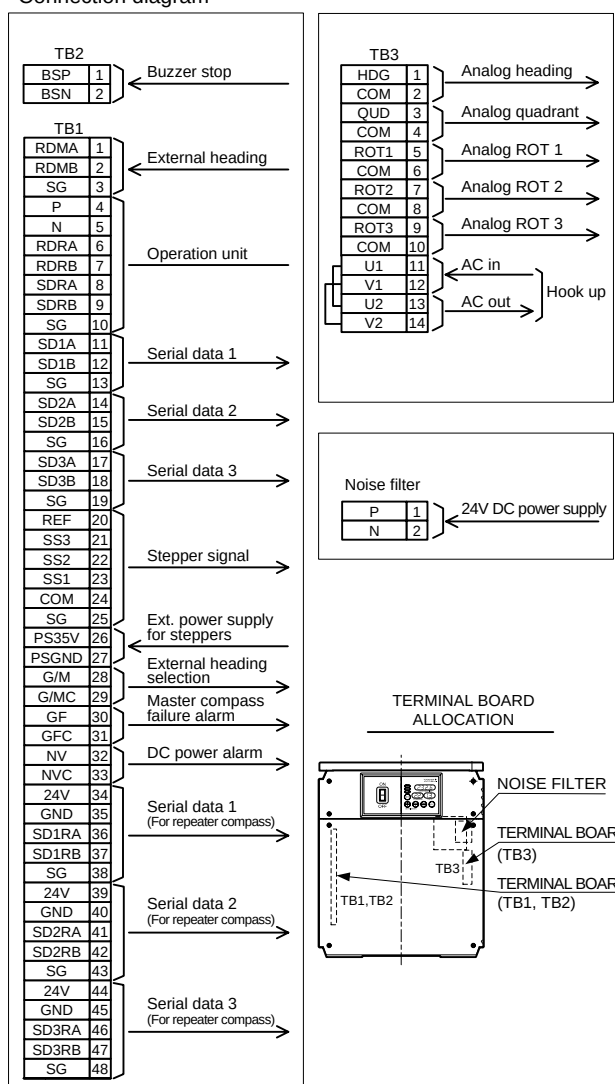


Master compass MKM026-X1...X7/option

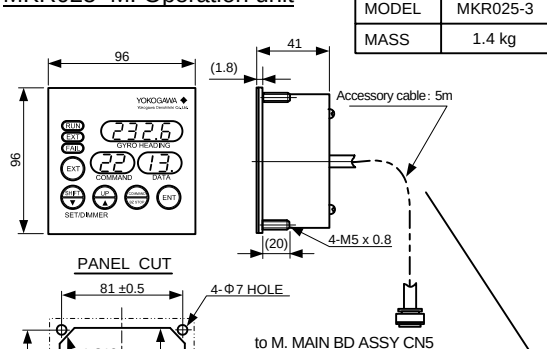
Model	Suffix	Specification
MKM026		Master compass
Style	-1 -2 -3 -4	Stand alone Built-in Pilot stand, with MKC326 Built-in Pilot stand, MKM026 only Built-in Console
Paint color	0	Not applicable
X2	1	Munsell 0.8Y2.5/0.4 (LAMP BLACK)
M. Operation unit installation	0	Outside of Mastercompass
X3	1	Inside of Master compass
Switch unit installation	-0	Outside of Mastercompass
X4	-1	Inside of Master compass
Standards	0 1 2	Not applicable JG MED (wheel mark)
X5		
Name plate	1	Japanese and English
X6	2	English
Applied to	-2	CMZ900S
X7		
Option	/48 /A1 /A2 /A3 /C	4800bps Repeater compass (else 9600bps) Output range of ROT 30°/min Output range of ROT 100°/min Output range of ROT 300°/min Chinese name plate

Note: 1) M. Operation unit (MKR025) and Switch unit (MKR026) are not included in Master compass (MKM026). Individual order must be placed for these items.
2) In case Master compass (MKM026) is built in Pilot stand, the other type of switch may be used instead of the Switch unit (MKR026).

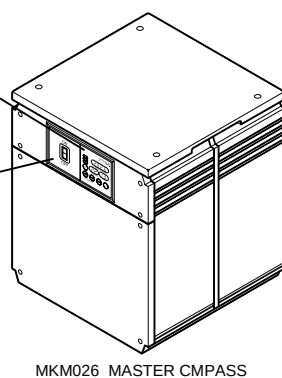
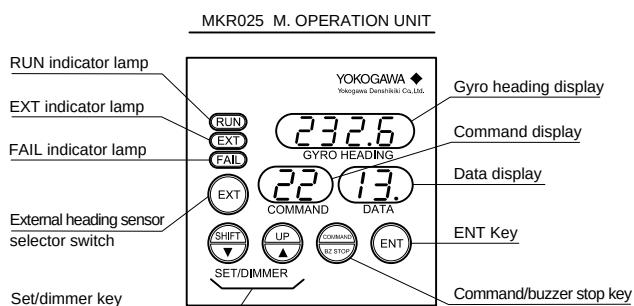
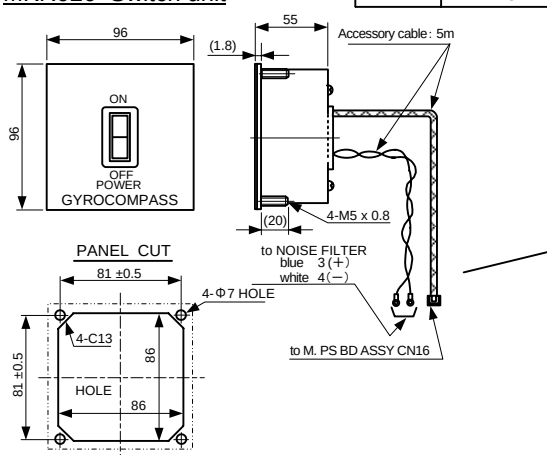
Connection diagram



MKR025 M. Operation unit



MKR026 Switch unit



M. Operation unit MKR025-X1...X3

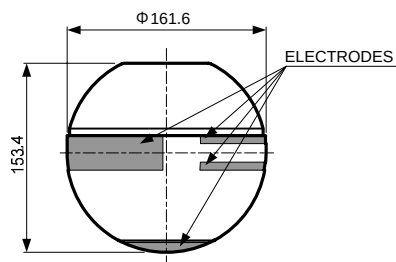
Model	Suffix	Specification
MKR025		M. Operation unit
Style	-1	Built-in Master compass
	-2	Built-in Pilot stand
X1	-3	Console mount
Seat key	E	English
X2	J	Japanese
Name plate	1	Japanese & English
X3	2	English

Switch unit MKR026-X1...X3

Model	Suffix	Specification
MKR026		Switch unit
Style	-1	Built-in Master compass
	-2	Built-in Pilot stand
X1	-3	Console mount
Seat key character	E	English
X2	J	Japanese
Name plate	1	Japanese & English
X3	2	English

MKT007 Gyrosphere

MODEL	MKT007-1
MASS	2.1 kg

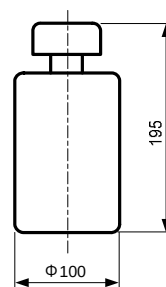


Gyrosphere MKT007-1

Model	Suffix	Specification
MKT007		Gyrosphere
Applied to	-1	CMZ900
X1		

MKZ115 Supporting liquid for installation

MODEL	MKZ115-1
MASS	1.2 kg



Supporting liquid for installation MKZ115-1/option

Model	Suffix	Specification
MKZ115		Supporting liquid for installation (1ℓ)
Name plate	-1	English
X1		
Option	/C	Chinese name plate

MKZ512 Spare parts

Spare parts MKZ512 -X1...X3/option

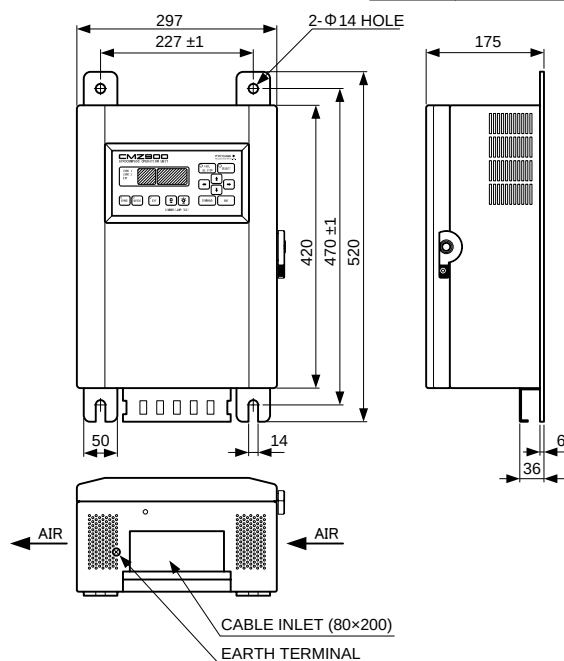
Model	Suffix	Specification
MKZ512		Spare parts
Applied to	-3	CMZ900S without DC back-up
X1	-4	CMZ900S with DC back-up
Box size	B	Large (plastic made)
X2	S	Small (plastic made)
Name plate	1	Japanese and English
X3	2	English
Option	/C	Chinese name plate

Note: Content of spare parts

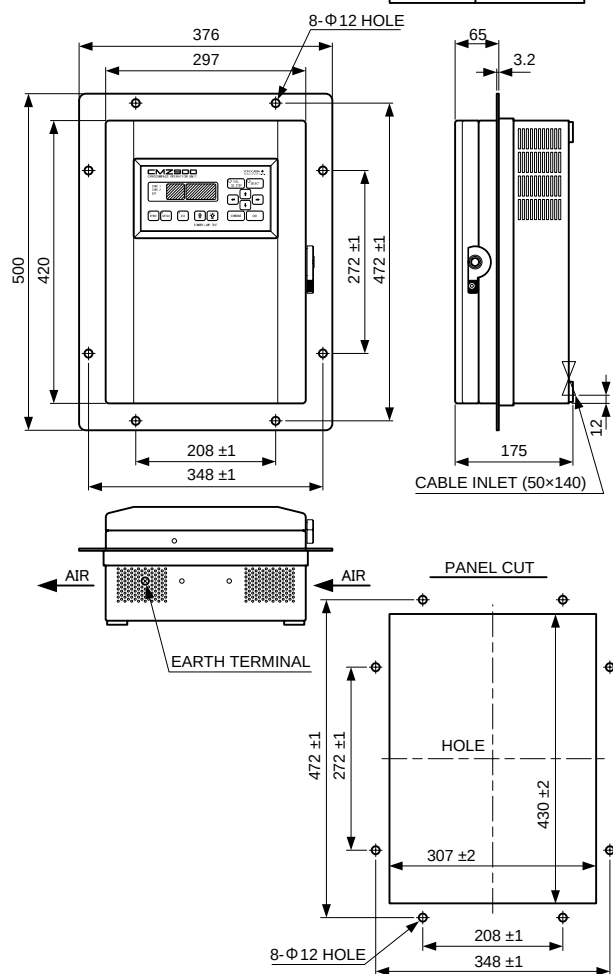
Item	CMZ900S without DC back-up	CMZ900S with DC back-up
Gyrosphere support	1 pc.	1 pc.
Container base	1 pc.	1 pc.
Injector	1 pc.	1 pc.
Meter cup	1 pc.	1 pc.
Funnel	1 pc.	1 pc.
Supporting liquid	1 liter	1 liter
Filter	10 pcs.	10 pcs.
Terminal screw driver	1 pc.	1 pc.
Illumination lamp	10 pcs. (28V 0.04A)	10 pcs. (28V 0.04A)
Fuse		4 pcs. (32V DC 15A)
Fuse	4 pcs. (250V AC 10A)	4 pcs. (250V AC 10A)
Fuse	8 pcs. (250V AC 2A)	4 pcs. (250V AC 2A)

MKC326 Control box

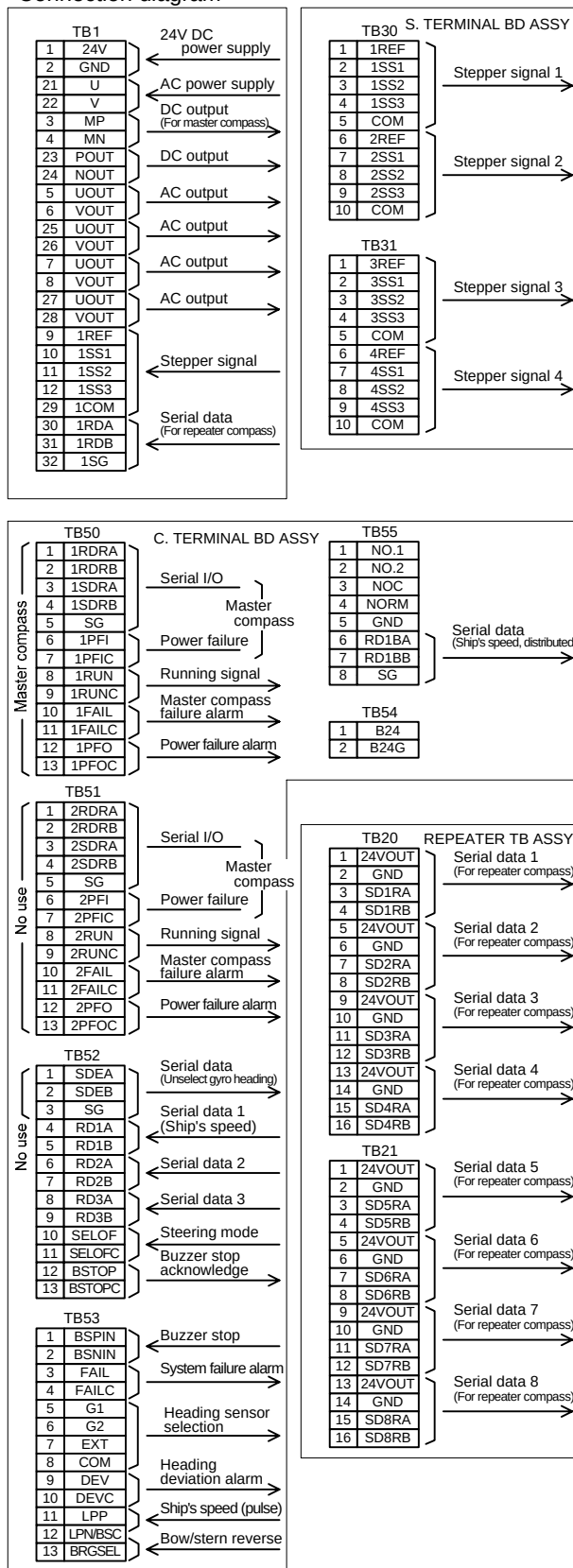
MODEL	MKC326-W1
MASS	17 kg



MODEL	MKC326-F1
MASS	17 kg



Connection diagram



Control box MKC326-X1...X7/option

Model	Suffix	Specification
MKC326		Control box
Style	-F1	Flush mount type
	-S1	Built-in Pilot stand (MKM026: in)
	-S2	Built-in Pilot stand (MKM026: out)
	-W1	Wall mount type
DC back-up	-0	No use
X2	-1	Use
C. Operation unit	1	Built-in Control box
	2	Built-in Pilot stand
	3	Console mount (cable: under 10m long)
	4	Console mount (cable: over 10m long)
Standards	0	Not applicable
	1	JG
	2	MED (wheel mark)
X4		
Name plate	-1	Japanese and English
X5	-2	English
Paint color	0	Not applicable
	1	Munsell 0.8Y2.5/0.4 (LAMP BLACK)
	2	Munsell 2.5G7/2
	3	Munsell 7.5BG7/2
Power supply	1	100V AC 50/60Hz single-phase, 24V DC
	2	110V AC 50/60Hz single-phase, 24V DC
	3	115V AC 50/60Hz single-phase, 24V DC
	4	220V AC 50/60Hz single-phase, 24V DC
X7		
Option	/C	Chinese name plate
	/S	Steppers reference 35V DC 1A max.

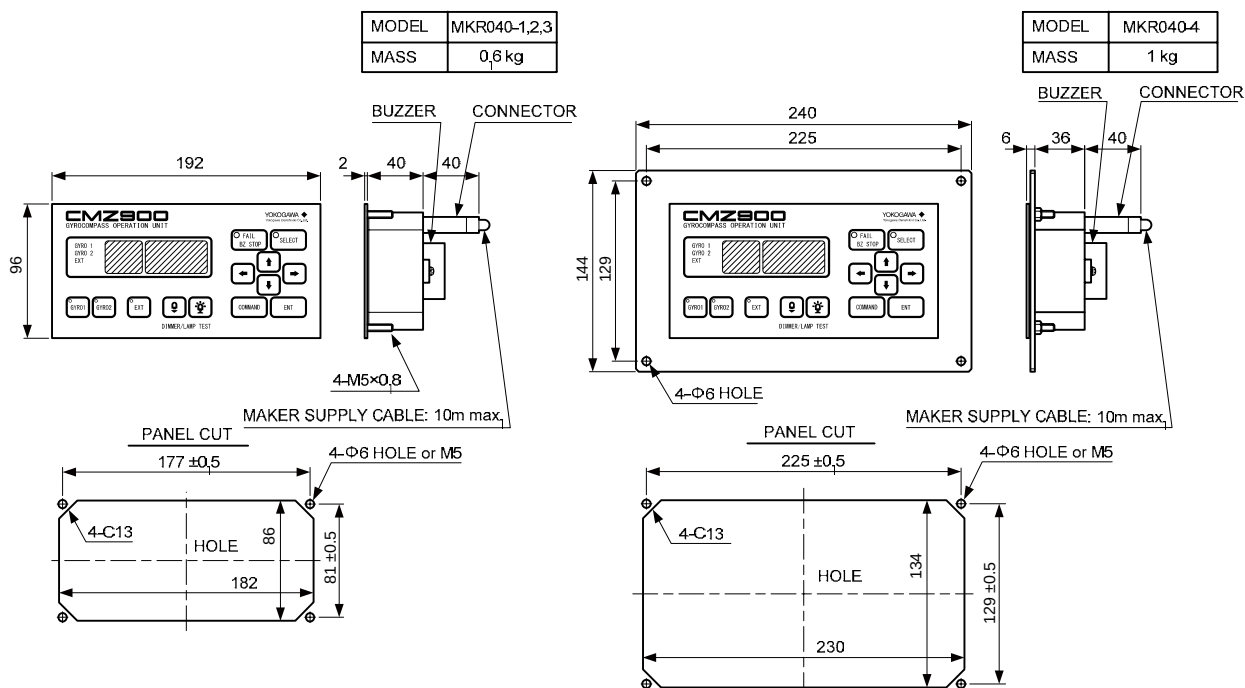
Note: 1) C. Operation unit (MKR040) is not included in Control box (MKC027).

Individual order must be placed for this item.

- 2) In case the Control box is flush or wall mount type (X1 = -F1 or -W1);
 - Junction unit (MKN018) is required, if the C. Operation unit is built in Pilot stand (X3 = 2).
 - Junction unit (MKN018) is required, if the C. Operation unit is built in Console with cable over 10m long (X3 = 4).

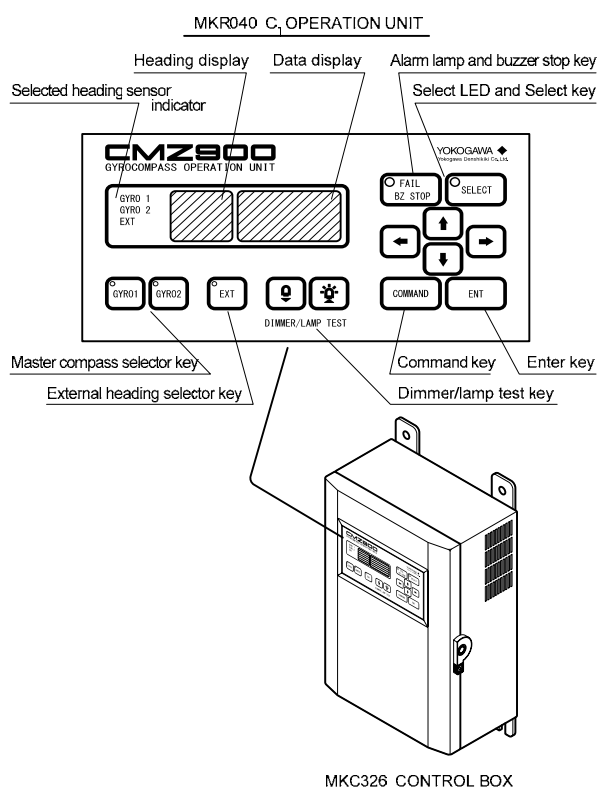
- 3) In case the Control box is built in Pilot stand (X1 = -S1 or -S2);
 - Junction unit (MKN018) is required, if the C. Operation unit is built in

MKR040 C. Operation unit

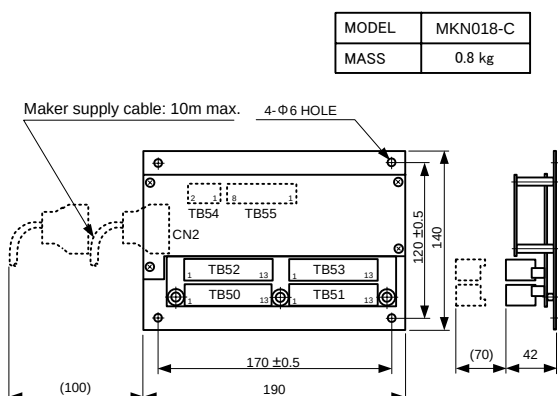


C. Operation unit MKR040-X1...X5/option

Model	Suffix	Specification
MKR040		C. Operation unit
Style	-1	Built-in Control box
	-2	Built-in Pilot stand
	-3	Console mount (size 96X192)
X1	-4	Console mount (size 144X240)
Seat key	E	English
X2		
Name plate	1	Japanese & English
X3	2	English
Cable length	-1	Built-in Control box or Pilot stand
	-2	1.5m
	-3	3.0m
	-4	5.0m
	-5	10.0m
X4		
Applied to	S	CMZ900B/S
X5		
Option	/E /L /M	Ext. serial data input: use Bow/stern reverse function MUTT function



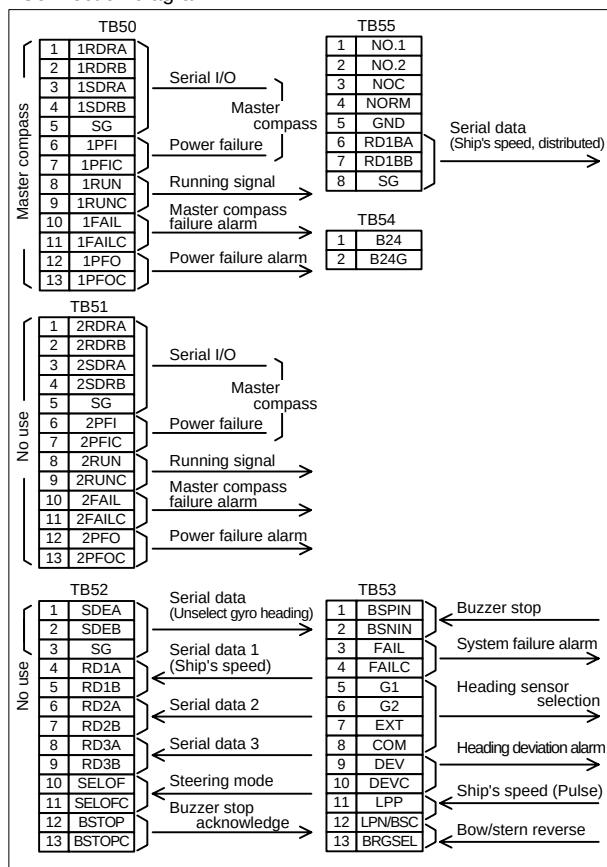
MKN018 Junction unit



Junction unit MKN018-X1X2

Model	Suffix	Specification
MKN018		Junction unit
Style	-C	Console mount
X1	-S	Built-in Pilot stand
Name plate	-1	Japanese & English
X2	-2	English

Connection diagram



End